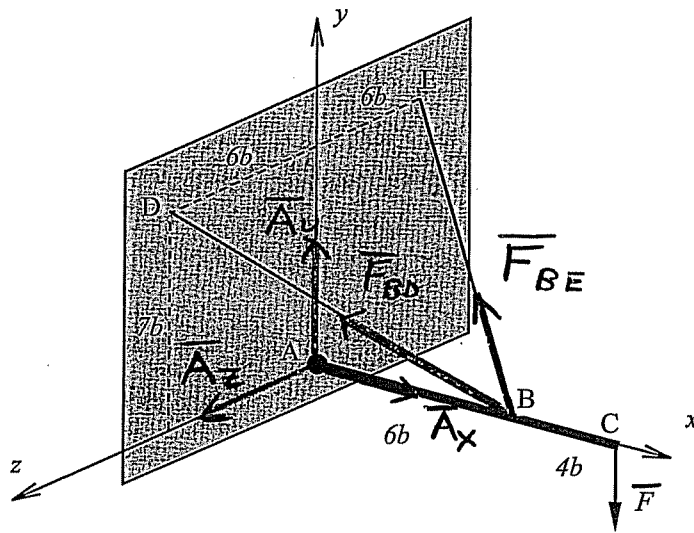


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1)



$$\sum \overline{M}_A = \overline{0}$$

$$\sum \overline{M}_A = \overline{r}_{AB} \times \overline{F}_{BD} + \overline{r}_{AB} \times \overline{F}_{BE} + \overline{r}_{AC} \times \overline{F}$$

$$\overline{r}_{AB} = 6b \overline{i} \quad \overline{r}_{AC} = 10b \overline{i}$$

$$\begin{aligned} \overline{F}_{BD} &= F_{BD} \cdot \frac{\overline{BD}}{|\overline{BD}|} = F_{BD} \cdot \frac{-6b \overline{i} + 7b \overline{j} + 6b \overline{k}}{\sqrt{(6b)^2 + (7b)^2 + (6b)^2}} = \\ &= \frac{F_{BD}}{11} (-6 \overline{i} + 7 \overline{j} + 6 \overline{k}) \end{aligned}$$

$$\overline{F}_{BE} = \frac{F_{BE}}{11} (-6 \overline{i} + 7 \overline{j} - 6 \overline{k})$$

$$\overline{F} = -F \overline{j} = -1 \overline{j} = -\overline{j} \text{ kN}$$

$$\sum \overline{M}_A = \frac{F_{BD}}{11} \begin{vmatrix} \overline{i} & \overline{j} & \overline{k} \\ 6b & 0 & 0 \\ -6 & 7 & 6 \end{vmatrix} + \frac{F_{BE}}{11} \begin{vmatrix} \overline{i} & \overline{j} & \overline{k} \\ 6b & 0 & 0 \\ -6 & 7 & -6 \end{vmatrix} + \begin{vmatrix} \overline{i} & \overline{j} & \overline{k} \\ 10b & 0 & 0 \\ 0 & -1 & 0 \end{vmatrix} = \overline{0}$$

$$\begin{Bmatrix} 0 \\ -\frac{F_{BD}}{11} \cdot 36b \\ \frac{F_{BD}}{11} \cdot 42b \end{Bmatrix} + \begin{Bmatrix} 0 \\ \frac{F_{BE}}{11} \cdot 36b \\ \frac{F_{BE}}{11} \cdot 42b \end{Bmatrix} + \begin{Bmatrix} 0 \\ 0 \\ -10b \end{Bmatrix} = \overline{0}$$

$$y\text{-led } \textcircled{1} \quad -\frac{F_{BD}}{11} \cdot 36b + \frac{F_{BE}}{11} \cdot 36b = 0 \Rightarrow F_{BD} = F_{BE}$$

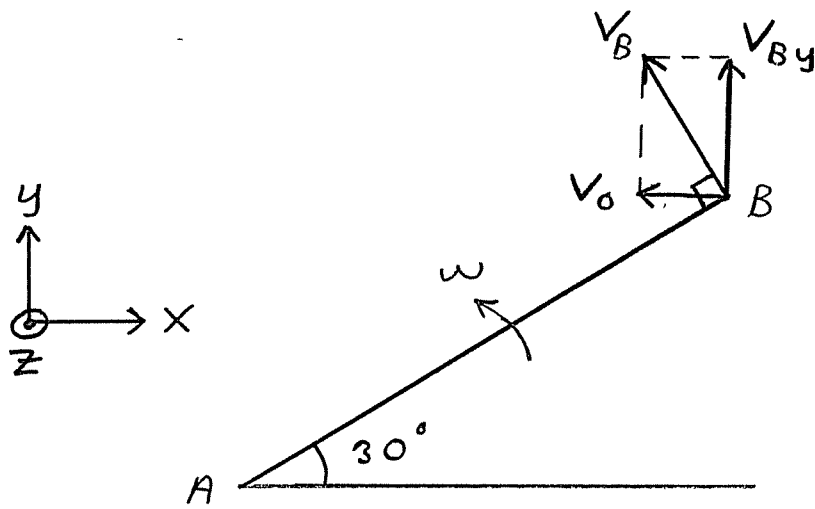
$$z\text{-led } \textcircled{2} \quad \frac{F_{BD}}{11} \cdot 42b + \frac{F_{BE}}{11} \cdot 42b - 10b = 0$$

$$\textcircled{2} \quad F_{BD} = \frac{55}{42} = 1,31 \text{ kN}$$

$$\text{Svar: } F_{BD} = F_{BE} = 1,31 \text{ kN}$$

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$$L = 0,5 \text{ m}$$

$$V_0 = 2 \text{ m/s}$$

$$\vec{V}_B = \vec{\omega} \times \vec{AB}$$

$$\vec{\omega} = \begin{Bmatrix} 0 \\ 0 \\ \omega \end{Bmatrix} \quad \vec{AB} = \begin{Bmatrix} 0,5 \cos 30^\circ \\ 0,5 \sin 30^\circ \\ 0 \end{Bmatrix}$$

$$\vec{V}_B = \begin{Bmatrix} 0 \\ 0 \\ \omega \end{Bmatrix} \times \begin{Bmatrix} 0,5 \cos 30^\circ \\ 0,25 \\ 0 \end{Bmatrix} = \begin{Bmatrix} -0,25 \omega \\ 0,5 \cos 30^\circ \cdot \omega \\ 0 \end{Bmatrix}$$

$$\begin{cases} V_{Bx} = -V_0 = -2 \text{ m/s} \\ V_{By} = -0,25 \omega \end{cases}$$

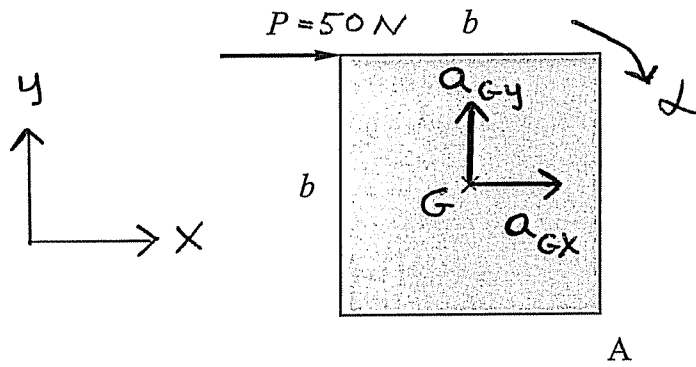
$$-2 = -0,25 \omega$$

$$\omega = 8 \text{ rad/s}$$

$$\underline{\underline{\text{Jawab: } \omega = 8 \text{ rad/s}}}$$

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$$\omega = 0$$

$$b = 1,0 \text{ m}$$

$$m = 5 \text{ kg}$$

$$\vec{a}_A = \vec{a}_G + \vec{\alpha} \times \vec{GA} + \vec{\omega} \times (\vec{\omega} \times \vec{GA})$$

$$\vec{a}_A = \vec{a}_G + \vec{\alpha} \times \vec{GA}$$

$$\sum F_x = m a_{Gx} \quad (1) \quad 50 = 5 a_{Gx}$$

$$\sum F_y = m a_{Gy} \quad (2) \quad 0 = 5 a_{Gy}$$

$$\sum M_G = I_G \cdot \alpha \quad (3) \quad 50 \cdot 0,5 = I_G \cdot \alpha$$

$$I_G = \frac{1}{12} m (a^2 + b^2) =$$

$$= \frac{1}{12} \cdot 5 (1^2 + 1^2) = \frac{5}{6}$$

$$= 0,8333 \text{ kg m}^2$$

$$(1) \quad a_{Gx} = 10 \text{ m/s}^2$$

$$(2) \quad a_{Gy} = 0$$

$$(3) \quad \alpha = 30 \text{ rad/s}^2$$

$$\vec{a}_A = \begin{Bmatrix} 10 \\ 0 \\ 0 \end{Bmatrix} + \begin{Bmatrix} 0 \\ 0 \\ -30 \end{Bmatrix} \times \begin{Bmatrix} 0,5 \\ -0,5 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 10 \\ 0 \\ 0 \end{Bmatrix} + \begin{Bmatrix} -15 \\ -15 \\ 0 \end{Bmatrix}$$

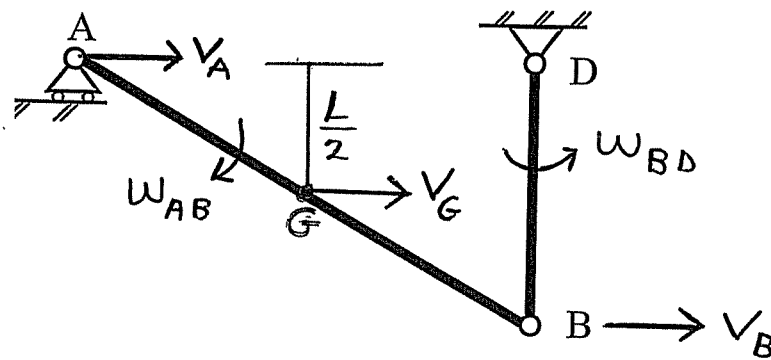
$$\vec{a}_A = \begin{Bmatrix} -5 \\ -15 \\ 0 \end{Bmatrix} \quad |\vec{a}_A| = \sqrt{(-5)^2 + (-15)^2} =$$

$$= \sqrt{250} \approx 15,8 \text{ m/s}^2$$

$$\underline{\underline{\text{Svar: } a_A = 15,8 \text{ m/s}^2}}$$

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Energiegleichungen

$$U = \Delta T + \Delta V_g + \Delta V_e$$

$$U = \Delta V_e = 0$$

AB
 V_A parallel med $V_B \Rightarrow \omega_{AB} = 0$

$$V_G = V_A$$

$$\begin{aligned} \Delta T &= T_2 - T_1 = \frac{1}{2} m V_G^2 + \frac{1}{2} I_G \omega^2 - 0 = \\ &= \frac{1}{2} \cdot 2m V_A^2 + 0 = \underline{m V_A^2} \end{aligned}$$

$$\Delta V_g = -2mg \cdot \frac{L}{2} = \underline{-mgL}$$

BD

$$V_B = V_A = \omega_{BD} \cdot L \Rightarrow \omega_{BD} = \frac{V_A}{L}$$

$$\Delta T = \frac{1}{2} I_0 \omega^2 = \frac{1}{2} \cdot \frac{1}{3} m L^2 \cdot \left(\frac{V_A}{L}\right)^2 = \underline{\frac{1}{6} m V_A^2}$$

$$\Delta V_g = -mg \cdot \frac{L}{2} = \underline{-\frac{1}{2} mgL}$$

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$$U = \Delta T + \Delta V_g + \Delta V_e$$

$$0 = \cancel{m} v_A^2 - \cancel{m} g L + \frac{1}{6} \cancel{m} v_A^2 - \frac{1}{2} \cancel{m} g L$$

$$\frac{7}{6} v_A^2 = \frac{3}{2} g L$$

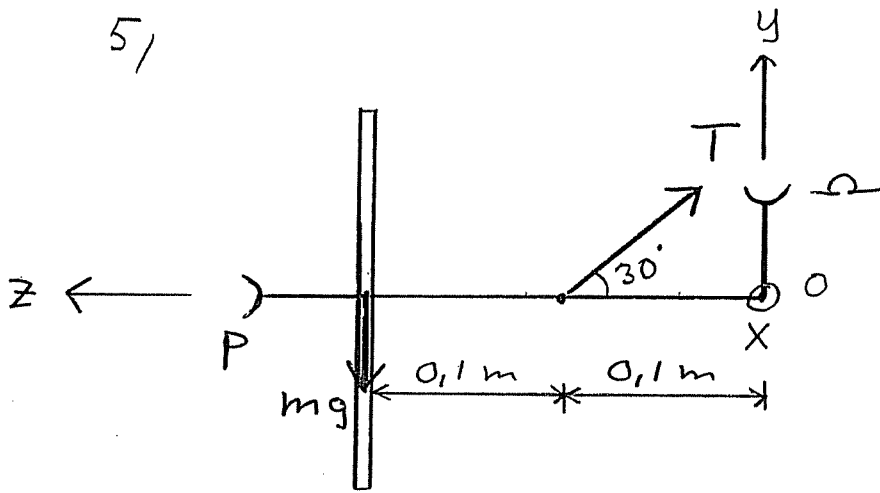
$$v_A^2 = \frac{9}{7} g L$$

$$v_A = 3 \sqrt{\frac{gL}{7}}$$

$$\underline{\underline{\text{Sum: } v_A = 3 \sqrt{\frac{gL}{7}}}}$$

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J punkten O
finns O_x, O_y
och O_z .

$$\begin{aligned} \omega &= 100 \text{ rad/s} \\ \Omega &= 0,5 \text{ rad/s} \\ r = b &= 0,1 \text{ m} \\ m &= 1,5 \text{ kg} \end{aligned}$$

$\bar{\omega}$ vid xyz

$$\bar{\omega} = \begin{Bmatrix} 0 \\ 0,5 \\ 0 \end{Bmatrix}$$

$$\bar{\omega} = \bar{\Omega} + \bar{\omega} = \begin{Bmatrix} 0 \\ 0,5 \\ 0 \end{Bmatrix} + \begin{Bmatrix} 0 \\ 0 \\ 100 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0,5 \\ 100 \end{Bmatrix}$$

$$\bar{M}_O = \left(\frac{d\bar{H}_O}{dt} \right)_{xyz} + \bar{\omega} \times \bar{H}_O$$

$$\bar{H}_O = \bar{I}_O \bar{\omega} = \begin{Bmatrix} - & 0 & 0 \\ - & I_{yy} & 0 \\ - & 0 & I_{zz} \end{Bmatrix} \begin{Bmatrix} 0 \\ 0,5 \\ 100 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0,5 I_{yy} \\ 100 I_{zz} \end{Bmatrix}$$

symmetri

$$\begin{Bmatrix} 1,5g \cdot 0,2 - T \sin 30^\circ \cdot 0,1 \\ 0 \\ 0 \end{Bmatrix} = \bar{0} + \begin{Bmatrix} 0 \\ 0,5 \\ 0 \end{Bmatrix} \times \begin{Bmatrix} 0 \\ 0,5 I_{yy} \\ 100 I_{zz} \end{Bmatrix}$$

$$\begin{Bmatrix} 0,3g - 0,05T \\ 0 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 50 I_{zz} \\ 0 \\ 0 \end{Bmatrix} \quad \begin{aligned} I_{zz} &= \frac{1}{2} m r^2 = \\ &= \frac{1}{2} \cdot 1,5 \cdot 0,1^2 = 0,0075 \text{ kg m}^2 \end{aligned}$$

$$0,3g - 0,05T = 50 \cdot 0,0075$$

$$T = \frac{0,3g - 0,375}{0,05} = 51,36 \text{ N}$$

Svar: $T = 51,4 \text{ N}$